

## Drive controller ACxx050A00S05.xx

The drive controller is designed for a mains connection (SELV or PELV) in a range of 24 V to 48 V DC.

For the logic supply is a power supply (SELV or PELV) with 24 V DC necessary. The drive controller is designed to connect several types of electrical motors and several position encoders.

The motor control is with integrated safety function STO (Safe torque off) (**not for DC brush motors**).



### Technical Data

#### Drive controller (ACxx050A00S05.xx)

##### Conformity

Machinery Directive 2006/42/EC  
EMC Directive 2014/30/EU

##### Safety related parameters

Application STO SIL 3 and Category 3, PL e

#### Rated Data

##### Power supply

Input voltage 24 V to 48 V DC  
SELV or PELV  
(return voltage capability to 60 V DC)

##### Logic Supply

Input voltage 24 V DC; SELV or PELV

##### Output current

	Continuous output current	Peak output current (t < 8 s)
AC05050A00S05.xx	5 A	10 A
AC08050A00S05.xx	8 A	16 A

#### Motor control

##### Supported types of motors

Servo motor, BLDC, DC brush motor  
2-phase stepper motor, 3-phase stepper motor,  
low-rating linear motors, LinMot

##### Supported position encoders

Resolver, Hiperface DSL, sine/cosine encoder,  
RS422 encoder, digital hall sensor, EnDat 2.2;  
LinMot und BiSS

##### I/O-Interface

1 digital 24V-SI-Input (dual-channel) and  
STO-Diagnostic contact (single-channel)  
4 digital 24V-Inputs  
2 analog inputs (-10 V to +10 V (12 bits))  
1 analog output (-10 V to +10 V (12 bits))  
Motor holding brake Max. 500 mA

##### Fieldbus interface

CAN (CANopen DS301 with DSP402)  
EtherCAT (CoE, FoE)

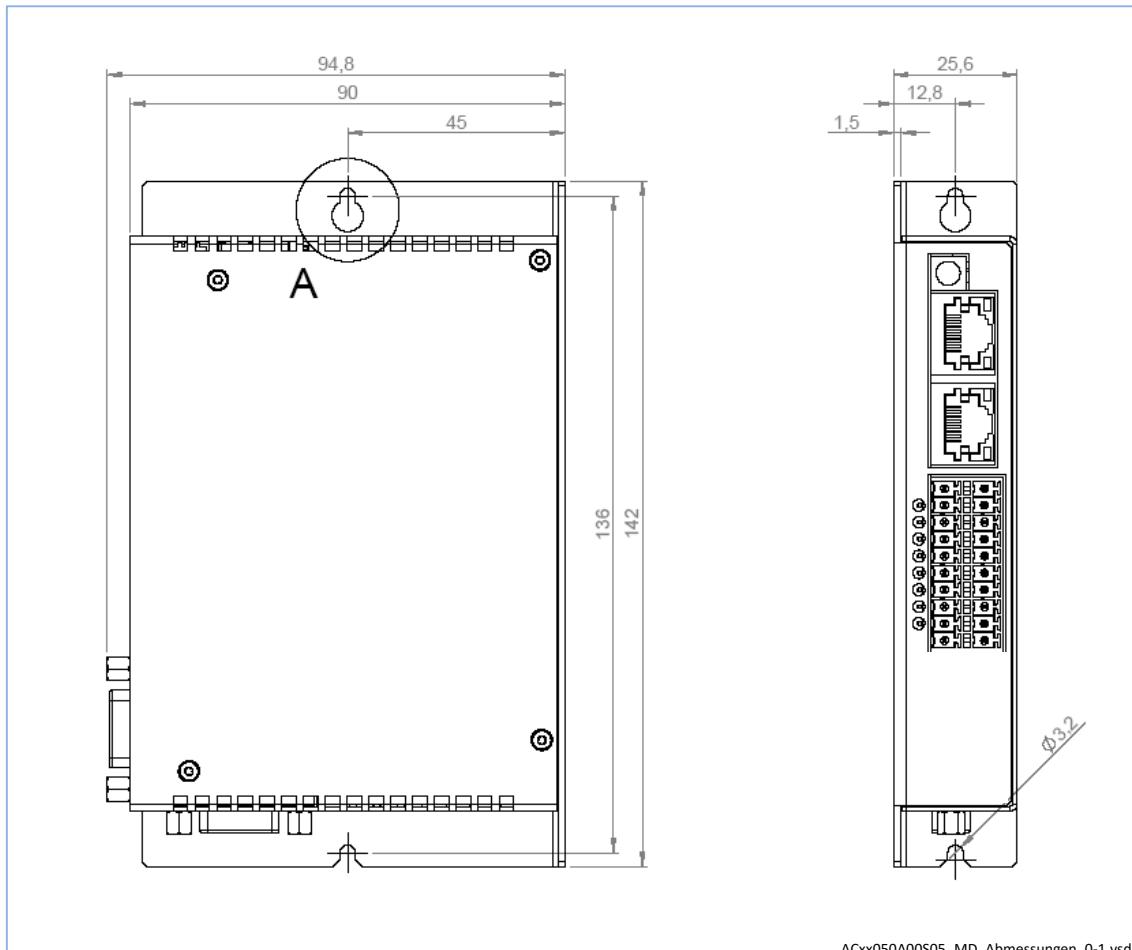
##### Engineering interface

USB-Interface Micro-USB  
SD-Card microSDHC



## Dimensions Drive controller

Drive controller	Weight [kg]	Height [mm]	Width [mm]	Depth [mm]
ACxx050A00S05.xx	0.41	142	25.6	94.8



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